13.1 Rotational Kinematics

1. The following figures show a rotating wheel. Determine the signs (+ or −) of ω and α.

   ![Rotating Wheel Diagram]

   ω ______  α ______
   ω ______  α ______
   ω ______  α ______
   ω ______  α ______

2. The figure shows a pendulum at one end point of its arc.
   a. At this point, is ω positive, negative, or zero? _____________
   b. At this point, is α positive, negative, or zero? _____________

3. The figures below show the radial acceleration vector $\vec{a}_r$ at four successive points on the trajectory of a particle moving in a counterclockwise circle.
   a. For each, draw the tangential acceleration vector $\vec{a}_t$ at points 2 and 3 or, if appropriate, write $\vec{a}_t = 0$.
   b. Determine if the particle’s angular acceleration $\alpha$ is positive (+), negative (−), or zero (0).

   ![Radial and Tangential Acceleration Diagrams]

   $\alpha = ________  \quad \alpha = ________  \quad \alpha = ________
4. The figure shows the $\theta$-versus-$t$ graph for a particle moving in a circle. The curves are all sections of parabolas.
   a. Draw the corresponding $\omega$-versus-$t$ and $\alpha$-versus-$t$ graphs. Notice that the horizontal tick marks are equally spaced.
   b. Write a description of the particle’s motion.

5. A wheel rolls to the left along a horizontal surface, up a ramp, then continues along the upper horizontal surface. Draw graphs for the wheel’s angular velocity $\omega$ and angular acceleration $\alpha$ as a functions of time.
13.2 Rotation About the Center of Mass

6. Is the center of mass of this dumbbell at point 1, 2, or 3? Explain.

7. Mark the center of mass of this object with an ×.

13.3 Torque

8. Five forces are applied to a door. For each, determine if the torque about the hinge is positive (+), negative (−), or zero (0).

9. Six forces, each of magnitude either $F$ or $2F$, are applied to a door. Rank in order, from largest to smallest, the six torques $\tau_1$ to $\tau_6$ about the hinge.
   
   Order:
   
   Explanation:
10. Four forces are applied to a rod that can pivot on an axle. For each force,
a. Use a black pen or pencil to draw the line of action.
b. Use a red pen or pencil to draw and label the moment arm, or state that \( d = 0 \).
c. Determine if the torque about the axle is positive (+), negative (−), or zero (0).

11. a. Draw a force vector at A whose torque about the axle is negative.
b. Draw a force vector at B whose torque about the axle is zero.
c. Draw a force vector at C whose torque about the axle is positive.

12. a. Draw a second force \( \vec{F}_2 \) that forms a couple with \( \vec{F}_1 \).
b. Draw and label the distance \( l \) between their lines of action.
c. Is the torque positive, negative, or zero? Explain.

13. The dumbbells below are all the same size, and the forces all have the same magnitude. Rank in order, from largest to smallest, the torques \( \tau_1 \), \( \tau_2 \), and \( \tau_3 \).

Order:

Explanation:
13.4 Rotational Dynamics

14. A student gives a quick push to a ball at the end of a massless, rigid rod, causing the ball to rotate clockwise in a horizontal circle. The rod’s pivot is frictionless.
   a. As the student is pushing, is the torque about the pivot positive, negative, or zero?
   
   b. After the push has ended, does the ball’s angular velocity
      i. Steadily increase?
      ii. Increase for awhile, then hold steady?
      iii. Hold steady?
      iv. Decrease for awhile, then hold steady?
      v. Steadily decrease?
      Explain the reason for your choice.
   
   c. Right after the push has ended, is the torque positive, negative, or zero? ________________

15. a. Rank in order, from largest to smallest, the torques $\tau_1$ to $\tau_4$.

   Order: 
   Explanation:

   b. Rank in order, from largest to smallest, the angular accelerations $\alpha_1$ to $\alpha_4$. 
16. The top graph shows the torque on a rotating wheel as a function of time. The wheel’s moment of inertia is 10 kg m$^2$. Draw graphs of $\alpha$-versus-$t$ and $\omega$-versus-$t$, assuming $\omega_0 = 0$.

17. The wheel turns on a frictionless axle. A string wrapped around the smaller diameter shaft is tied to a block. The block is released at $t = 0$ s and hits the ground at $t = t_1$.

   a. Draw a graph of $\omega$-versus-$t$ for the wheel, starting at $t = 0$ s and continuing to some time $t > t_1$.

   b. Is the magnitude of the block’s downward acceleration greater than $g$, less than $g$, or equal to $g$? Explain.
18. The moment of inertia of a uniform rod about an axis through its center is $\frac{1}{12} ML^2$. The moment of inertia about an axis at one end is $\frac{1}{3} ML^2$. Explain why the moment of inertia is larger about the end than about the center.

19. You have two steel spheres. Sphere 2 has twice the radius of sphere 1. By what factor does the moment of inertia $I_2$ of sphere 2 exceed the moment of inertia $I_1$ of sphere 1?

20. The professor hands you two spheres. They have the same mass, the same radius, and the same exterior surface. The professor claims that one is a solid sphere and that the other is hollow. Can you determine which is which without cutting them open? If so, how? If not, why not?

21. Rank in order, from largest to smallest, the moments of inertia $I_1$, $I_2$, and $I_3$.

Order:

Explanation:
13.5 Rotation About a Fixed Axis

22. A square plate can rotate about an axle through its center. Four forces of equal magnitude are applied to different points on the plate. The forces turn as the plate rotates, maintaining the same orientation with respect to the plate. Rank in order, from largest to smallest, the angular accelerations $\alpha_1$ to $\alpha_4$.

Order:

Explanation:

23. A solid cylinder and a cylindrical shell have the same mass, same radius, and turn on frictionless, horizontal axles. (The cylindrical shell has light-weight spokes connecting the shell to the axle.) A rope is wrapped around each cylinder and tied to a block. The blocks have the same mass and are held the same height above the ground. Both blocks are released simultaneously. The ropes do not slip.

Which block hits the ground first? Or is it a tie? Explain.

13.6 Rigid Body Equilibrium

24. A uniform rod pivots about a frictionless, horizontal axle through its center. It is placed on a stand, held motionless in the position shown, then gently released. On the right side of the figure, draw the final, equilibrium position of the rod. Explain your reasoning.
25. The dumbbell has masses $m$ and $2m$. Force $\vec{F}_1$ acts on mass $m$ in the direction shown. Is there a force $\vec{F}_2$ that can act on mass $2m$ such that the dumbbell moves with pure translational motion, without any rotation? If so, draw $\vec{F}_2$, making sure that its length shows the magnitude of $\vec{F}_2$ relative to $\vec{F}_1$. If not, explain why not.

26. Forces $\vec{F}_1$ and $\vec{F}_2$ have the same magnitude and are applied to the corners of a square plate. Is there a single force $\vec{F}_3$ that, if applied to the appropriate point on the plate, will cause the plate to be in total equilibrium? If so, draw it, making sure it has the right position, orientation, and length. If not, explain why not.

27. The steel girder of a bridge is supported by four posts. A truck is driving across the bridge and is at the position shown.
   a. On the figure, draw force arrows to show all forces acting on the steel girder.
   b. Is the net torque about the left support post positive, negative, or zero? Explain.
13.7 Rotational Energy

28. The figure shows four identical particles moving in circles. Rank in order, from largest to smallest, their rotational kinetic energies $K_1$ to $K_4$.

Order:
Explanation:

29. If the angular velocity $\omega$ is held constant, by what factor must $R$ change to double the rotational kinetic energy?

13.8 Rolling Motion

30. A wheel is rolling along a horizontal surface with the center-of-mass velocity shown. Draw the velocity vector $\vec{v}$ at points 1 to 4 on the rim of the wheel.
31. A wheel is rolling along a horizontal surface with the center-of-mass velocity shown. Draw the velocity vector \( \vec{v} \) at points 1 to 3 on the wheel.

32. If a solid disk and a circular hoop of the same mass and radius are released from rest at the top of a ramp and allowed to roll to the bottom, the disk will get to the bottom first. Without referring to equations, explain why this is so.
13.9 The Vector Description of Rotational Motion

13.10 Angular Momentum of a Rigid Body

33. For each vector pair $\vec{A}$ and $\vec{B}$ shown below, determine if $\vec{A} \times \vec{B}$ points into the page, out of the page, or is zero.

- $\vec{A} \times \vec{B}$
- $\vec{A} \times \vec{B}$
- $\vec{A} \times \vec{B}$
- $\vec{A} \times \vec{B}$

34. Each figure below shows $\vec{A}$ and $\vec{A} \times \vec{B}$. Determine if $\vec{B}$ is in the plane of the page or perpendicular to the page. If $\vec{B}$ is in the plane of the page, draw it. If $\vec{B}$ is perpendicular to the page, state whether $\vec{B}$ points into the page or out of the page.

- $\vec{A} \times \vec{B}$
- $\vec{A} \times \vec{B}$
- $\vec{A} \times \vec{B}$

35. Draw the angular velocity vector on each of the rotating wheels.

- a.
- b.
- c.

36. The figures below show a force acting on a particle. For each, draw the torque vector for the torque about the origin.

- Place the tail of the torque vector at the origin.
- Draw the vector large and straight (use a ruler!) so that its direction is clear. Use dotted lines from the tip of the vector to the axes to show the plane in which the vector lies.

- a.
- b.
- c.
37. The figures below show a particle with velocity \( \vec{v} \). For each, draw the angular momentum vector \( \vec{L} \) for the angular momentum relative to the origin. Place the tail of the angular momentum vector at the origin.

![Diagram](image)

38. Rank in order, from largest to smallest, the angular momenta \( L_1 \) to \( L_4 \).

![Diagram](image)

Order:
Explanation:

39. Is the angular momentum of disk 2 larger than, smaller than, or equal to the angular momentum of disk 1? Explain.